INTEGRATED CIRCUITS



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Philips Semiconductors

SSTV16859

FEATURES

- Stub-series terminated logic for 2.5 V V_{DD} (SSTL_2)
- Optimized for stacked DDR (Double Data Rate) SDRAM applications
- Supports SSTL_2 signal inputs as per JESD 8–9
- Flow-through architecture optimizes PCB layout
- ESD classification testing is done to JEDEC Standard JESD22. Protection exceeds 2000 V to HBM per method A114.
- Latch-up testing is done to JEDEC Standard JESD78, which exceeds 100 mA.
- Supports efficient low power standby operation
- Full DDR 200/266 solution for stacked DIMMs at 2.5 V when used with PCKV857
- See SSTV16857 for JEDEC compliant register support in unstacked DIMM applications
- See SSTV16856 for driver/buffer version with mode select.

DESCRIPTION

The SSTV16859 is a 13-bit to 26-bit SSTL_2 registered driver with differential clock inputs, designed to operate between 2.3 V and 2.7 V. All inputs are compatible with the JEDEC standard for SSTL_2 with V_{REF} normally at 0.5^*V_{DD} , except the LVCMOS reset (RESET) input. All outputs are SSTL_2, Class II compatible which can be used for standard stub-series applications or capacitive loads. Master reset (RESET) asynchronously resets all registers to zero.

The SSTV16859 is intended to be incorporated into standard DIMM (Dual In-Line Memory Module) designs defined by JEDEC, such as

DDR (Double Data Rate) SDRAM and SDRAM II Memory Modules. Different from traditional SDRAM, DDR SDRAM transfers data on both clock edges (rising and falling), thus doubling the peak bus bandwidth. A DDR DRAM rated at 133 MHz will have a burst rate of 266 MHz.

The device data inputs consist of different receivers. One differential input is tied to the input pin while the other is tied to a reference input pad, which is shared by all inputs.

The clock input is fully differential (CK and \overline{CK}) to be compatible with DRAM devices that are installed on the DIMM. Data are registered at the crossing of CK going high, and \overline{CK} going low. However, since the control inputs to the SDRAM change at only half the data rate, the device must only change state on the positive transition of the CK signal. In order to be able to provide defined outputs from the device even before a stable clock has been supplied, the device has an asynchronous input pin (RESET), which when held to the LOW state, resets all registers and all outputs to the LOW state.

The device supports low-power standby operation. When RESET is low, the differential input receivers are disabled, and undriven (floating) data, clock, and reference voltage (V_{REF}) inputs are allowed. In addition, when RESET is low, all registers are reset, and all outputs are forced low. The LVCMOS RESET input must always be held at a valid logic high or low level.

To ensure defined outputs from the register before a stable clock has been supplied, $\overline{\text{RESET}}$ must be held in the low state during power-up.

In the DDR DIMM application, RESET is specified to be completely asynchronous with respect to CK and \overline{CK} . Therefore, no timing relationship can be guaranteed between the two. When entering RESET, the register will be cleared and the outputs will be driven low. As long as the data inputs are low, and the clock is stable during the time from the low-to-high transition of RESET until the input receivers are fully enabled, the outputs will remain low.

Available in 64-pin plastic thin shrink small outline package.

QUICK REFERENCE DATA

GND = 0 V; $T_{amb} = 25^{\circ}C$; $t_r = t_f \le 2.5 \text{ ns}$

SYMBOL	PARAMETER	CONDITIONS	TYPICAL	UNIT
t _{PHL} /t _{PLH}	Propagation delay; CLK to Qn	$C_L = 30 \text{ pF}; \text{ V}_{DD} = 2.5 \text{ V}$	2.4	ns
Cl	Input capacitance	V _{CC} = 2.5 V	2.7	pF

NOTE:

1. C_{PD} is used to determine the dynamic power dissipation (P_D in μ W) $P_D = C_{PD} \times V_{CC}^2 \times f_i + \Sigma (C_L \times V_{CC}^2 \times f_o)$ where: $f_i =$ input frequency in MHz; $C_L =$ output load capacity in pF; $f_o =$ output frequency in MHz; $V_{CC} =$ supply voltage in V;

 $\Sigma (C_L \times V_{CC}^2 \times f_0) = \text{sum of the outputs.}$

ORDERING INFORMATION

PACKAGES	TEMPERATURE RANGE	ORDER CODE	DWG NUMBER
64-Pin Plastic TSSOP	0 to +70 °C	SSTV16859DGG	SOT646AA1
96-Ball Plastic LFBGA	0 to +70 °C	SSTV16859EC	SOT536-1
56-Terminal Plastic HVQFN	0 to +70 °C	SSTV16859BS	SOT684-1

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PIN CONFIGURATION

Q13A [64	Voo	
0124	2	63	GND	
0114	3	62	D13	
	4	61	D12	
	5	60	Vaa	
Vaa (6	59	Vaa	
	7	58	GND	
	8	57	D11	
	9	56	D10	
	10	55	D9	
Q5A [11	54	GND	
Q4A [12	53	D8	
Q3A [13	52	D7	
Q2A	14	51	RESET	
GND	15	50	GND	
Q1A	16	49	CK	
Q13B	17	48	СК	
V _{DD}	18	47	V _{DD}	
Q12B	19	46	V _{DD}	
Q11B	20	45	V _{REF}	
Q10B	21	44	D6	
Q9B	22	43	GND	
Q8B	23	42	D5	
Q7B	24	41	D4	
Q6B	25	40	D3	
GND [26	39	GND	
V _{DD} [27	38	V _{DD}	
Q5B	28	37	V _{DD}	
Q4B	29	36	D2	
Q3B	30	35	D1	
Q2B	31	34	GND	
Q1B [32	33	V _{DD}	
				014/00=15
				57700749

PIN DESCRIPTION

PIN NUMBER	SYMBOL	NAME AND FUNCTION
1, 2, 3, 4, 5, 8, 9, 10, 11, 12, 13, 14, 16	Q13A–Q1A	Data output
17, 19, 20, 21, 22, 23, 24, 25, 28, 29, 30, 31, 32	Q13B–Q1B	Data output
6, 18, 27, 33, 37, 38, 46, 47, 59, 60, 64	V _{DD}	Power supply voltage
7, 15, 26, 34, 39, 43, 50, 54, 58, 63	GND	Ground
35, 36, 40, 41, 42, 44, 52, 53, 55, 56, 57, 61, 62	D1–D13	Data input: clocked in on the crossing of the rising edge of CK and the falling edge of CK
45	V _{REF}	Input reference voltage
48, 49	CK, CK	Positive and negative master clock input
51	RESET	Asynchronous reset input: resets registers and disables data and clock differential input receivers

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56-TERMINAL CONFIGURATION



TERMINAL DESCRIPTION

TERMINAL NUMBER	SYMBOL	NAME AND FUNCTION
1, 2, 3, 4, 5, 6, 7, 50, 51, 52, 53, 54, 56	Q13A–Q1A	Data output
10, 11, 12, 13, 14, 15, 16, 18, 19, 20, 21, 22	Q13B–Q1B	Data output
9, 17, 23, 27, 34, 44, 49, 55	V _{DDQ}	Power supply voltage
26, 33, 45	V _{DDI}	Power supply voltage
37, 48	GND	Ground
24, 25, 28, 29, 30, 31, 39, 40, 41, 42, 43, 46, 47	D1–D13	Data input: clocked in on the crossing of the rising edge of CK and the falling edge of CK
32	V _{REF}	Input reference voltage
35, 36	CK, CK	Positive and negative master clock input
51	RESET	Asynchronous reset input: resets registers and disables data and clock differential input receivers

BALL CONFIGURATION

1 2 3 4 5 6 A B Q12A Q13A GND GND C Q10A Q11A GND GND D Q8A Q9A VDDQ VDDQ D13 D12 E Q6A Q7A VDDQ VDDQ D11 D10 F Q4A Q5A VDDQ VDDQ D11 D10 F Q4A Q5A VDDQ VDDQ D9 D8 G Q2A Q3A GND GND D7 RESET H Q1A Q13B GND VDDQ VDDQ D9 D8 G Q2A Q3A GND GND D7 RESET H Q1A Q13B GND VDQ VDDQ D5 D6 K Q10B Q9B VDDQ VDDQ D3 D4 N Q4B Q3B <						_	
A B Q12A Q13A GND GND GND C Q10A Q11A GND GND GND D Q8A Q9A VDDQ VDDQ D13 D12 E Q6A Q7A VDDQ VDDQ D11 D10 F Q4A Q5A VDDQ VDDQ D9 D8 G Q2A Q3A GND GND D7 RESET H Q1A Q13B GND GND D7 RESET J Q12B Q11B GND VDDQ D0 CK J Q12B Q11B GND VDDQ D5 D6 K Q10B Q5B VDDQ VDDQ D3 D4 N Q4B Q3B GND GND D1 D2 P Q2B Q1B GND GND D1 D2 P		1	2	3	4	5	6
B Q12A Q13A GND GND — — C Q10A Q11A GND GND — — D Q8A Q9A VDDQ VDDQ D13 D12 E Q6A Q7A VDDQ VDDQ D11 D10 F Q4A Q5A VDDQ VDDQ D9 D8 G Q2A Q3A GND GND D7 RESET H Q1A Q13B GND GND — CK J Q12B Q11B GND VDDQ D5 D6 K Q10B Q3B VDDQ VDDQ D3 D4 L Q8B Q7B VDDQ D10 D2 D6 K Q10B Q3B Q10D VDDQ D3 D4 N Q4B Q3B GND GND — — P Q2B Q1B <	A	_	_	_	—	—	_
C Q10A Q11A GND GND D Q8A Q9A VDDQ VDDQ D13 D12 E Q6A Q7A VDDQ VDDQ D13 D12 F Q6A Q7A VDDQ VDDQ D11 D10 F Q4A Q5A VDDQ VDDQ D9 D8 G Q2A Q3A GND GND D7 RESET H Q1A Q13B GND GND D7 RESET J Q12B Q11B GND VDQ CK J Q12B Q1B GND VDQ L Q4B Q3B VDQ VDQ D5 D6 K Q10B Q5B VDQ VDQ D3 D4 L Q4B Q3B GND GND D1 D2 M Q4B Q3B GND GND D1 D2 P Q2B Q1B GND	В	Q12A	Q13A	GND	GND	_	_
D Q8A Q9A V _{DDQ} V _{DDQ} D13 D12 E Q6A Q7A V _{DDQ} V _{DDQ} D11 D10 F Q4A Q5A V _{DDQ} V _{DDQ} D9 D8 G Q2A Q3A GND GND D7 RESET H Q1A Q13B GND GND CK J Q12B Q11B GND V _{DDQ} D9 D8 K Q10B Q13B GND GND CK J Q12B Q11B GND V _{DEQ} L Q8B Q9B V _{DDQ} V _{DDQ} D5 D6 M Q6B Q5B V _{DDQ} V _{DDQ} D1 D2 P Q2B Q1B GND GND D1 D2 R - Q10B Q1B	С	Q10A	Q11A	GND	GND	_	_
E Q6A Q7A VDDQ VDDQ D11 D10 F Q4A Q5A VDDQ VDDQ D9 D8 G Q2A Q3A GND GND D7 RESET H Q1A Q13B GND GND CK J Q12B Q11B GND VDDQ CK L Q10B Q9B VDDQ VDDQ L Q18B Q7B VDDQ UDDQ L Q10B Q9B VDDQ VDDQ L Q8B Q7B VDDQ UDDQ D5 D6 M Q6B Q5B VDDQ VDDQ D3 D4 N Q4B Q3B GND GND P Q2B Q1B GND GND R -	D	Q8A	Q9A	V _{DDQ}	V _{DDQ}	D13	D12
F Q4A Q5A V _{DDQ} V _{DDQ} D9 D8 G Q2A Q3A GND GND D7 RESET H Q1A Q13B GND GND — CK J Q12B Q11B GND V _{DDQ} — CK K Q10B Q9B V _{DDQ} V _{DDQ} — — L Q8B Q7B V _{DDQ} V _{DDQ} D5 D6 M Q6B Q5B V _{DDQ} V _{DDQ} D3 D4 Q Q2B Q1B GND GND D1 D2 M Q6B Q3B GND GND D1 D2 P Q2B Q1B GND GND — — R — — — — — — — M Q6B Q3B GND GND D1 D2 _ P — <td>E</td> <td>Q6A</td> <td>Q7A</td> <td>V_{DDQ}</td> <td>V_{DDQ}</td> <td>D11</td> <td>D10</td>	E	Q6A	Q7A	V _{DDQ}	V _{DDQ}	D11	D10
GQ2AQ3AGNDGNDD7RESETHQ1AQ13BGNDGNDCKJQ12BQ11BGNDV _{REF} CKKQ10BQ9BV _{DDQ} V _{DDQ} LQ8BQ7BV _{DDQ} V _{DDQ} D5D6MQ6BQ5BV _{DDQ} V _{DDQ} D3D4NQ4BQ3BGNDGNDD1D2PQ2BQ1BGNDGNDT	F	Q4A	Q5A	V _{DDQ}	V _{DDQ}	D9	D8
H Q1A Q13B GND GND — \overline{CK} J Q12B Q11B GND V_{REF} — CK K Q10B Q9B V_{DDQ} V_{DDQ} — — L Q8B Q7B V_{DDQ} V_{DDQ} D5 D6 M Q6B Q5B V_{DDQ} V_{DDQ} D3 D4 N Q4B Q3B GND GND D1 D2 P Q2B Q1B GND GND — — R — — — — — — T — — — — — —	G	Q2A	Q3A	GND	GND	D7	RESET
J Q12B Q11B GND V _{REF} CK K Q10B Q9B V _{DDQ} V _{DDQ} L Q8B Q7B V _{DDQ} V _{DDQ} D5 D6 M Q6B Q5B V _{DDQ} V _{DDQ} D3 D4 N Q4B Q3B GND GND D1 D2 P Q2B Q1B GND GND T	н	Q1A	Q13B	GND	GND	_	СК
K Q10B Q9B VDDQ VDDQ L Q8B Q7B VDDQ VDDQ D5 D6 M Q6B Q5B VDDQ VDDQ D3 D4 N Q4B Q3B GND GND D1 D2 P Q2B Q1B GND GND R - - - - - - T - - - - - -	J	Q12B	Q11B	GND	V _{REF}	_	СК
L Q8B Q7B V _{DDQ} V _{DDQ} D5 D6 M Q6B Q5B V _{DDQ} V _{DDQ} D3 D4 N Q4B Q3B GND GND D1 D2 P Q2B Q1B GND GND R - - - - - - T - - - - - -	к	Q10B	Q9B	V _{DDQ}	V _{DDQ}	_	_
M Q6B Q5B V _{DDQ} V _{DDQ} D3 D4 N Q4B Q3B GND GND D1 D2 P Q2B Q1B GND GND R - - - - - - T - - - - - -	L	Q8B	Q7B	V _{DDQ}	V _{DDQ}	D5	D6
N Q4B Q3B GND GND D1 D2 P Q2B Q1B GND GND R T	М	Q6B	Q5B	V _{DDQ}	V _{DDQ}	D3	D4
P Q2B Q1B GND GND — — R — — — — — — — T — — — — — — —	Ν	Q4B	Q3B	GND	GND	D1	D2
R	Р	Q2B	Q1B	GND	GND	_	_
т — — — — — —	R	_	-	_	_	_	_
	т	_	_		_	_	_

LOGIC DIAGRAM



FUNCTION TABLE (each flip flop)

INPUTS				OUTPUT
RESET	CLK	CLK	D	Q

Н	\uparrow	Ļ	L	L
Н	↑	Ļ	Н	Н
Н	L or H	L or H	Х	Q ₀
L	X or floating	X or floating	X or floating	L

H = High voltage level

L = Low voltage level \downarrow = High-to-Low transition \uparrow = Low-to-High transition

X = Don't care

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ABSOLUTE MAXIMUM RATINGS¹

CVMPOL	DADAMETER	CONDITION	L	LINUT	
STMBOL	PARAMETER	CONDITION	MIN	MAX	UNIT
V _{DD}	Supply voltage range		-0.5	+3.6	V
VI	Input voltage range	Notes 2 and 3	-0.5	V _{DD} + 0.5	V
Vo	Output voltage range	Notes 2 and 3	-0.5	V _{DD} + 0.5	V
I _{IK}	Input clamp current	$V_{I} < 0 \text{ or } V_{I} > V_{DD}$	—	±50	mA
I _{ОК}	Output clamp current	$V_{O} < 0 \text{ or } V_{O} > V_{DD}$	—	±50	mA
Ι _Ο	Continuous output current	$V_{O} = 0$ to V_{DD}	—	±50	mA
	Continuous current through each V _{DD} or GND		_	±100	mA
T _{stg}	Storage temperature range		-65	+150	°C

NOTES:

1. Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

2. The input and output negative-voltage ratings may be exceeded if the input and output current ratings are observed.

3. This value is limited to 3.6 V maximum.

4. The performance capability of a high-performance integrated circuit in conjunction with its thermal environment can create junction temperatures that are detrimental to reliability. The maximum junction temperature of this integrated circuit should not exceed 150°C.

RECOMMENDED OPERATING CONDITIONS¹

SYMBOL	PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNIT
V _{DD}	Supply voltage		V _{DD}	—	2.7	V
V _{REF}	Reference voltage $(V_{REF} = V_{DD}/2)$		1.15	1.25	1.35	V
V _{TT}	Termination voltage		V _{REF} – 40 mV	V_{REF}	V _{REF} + 40 mV	V
VI	Input voltage		0	_	V _{DD}	V
VIH	AC HIGH-level input voltage	Data inputs	V _{REF} + 310 mV	—	—	V
V _{IL}	AC LOW-level input voltage	Data inputs	—	—	$V_{REF} - 310 \text{ mV}$	V
V _{IH}	DC HIGH-level input voltage	Data inputs	V _{REF} + 150 mV	—	—	V
V _{IL}	DC LOW-level input voltage	Data inputs	—	—	V _{REF} – 150 mV	V
V _{IH}	HIGH-level input voltage	RESET	1.7	—	V _{DD}	V
V _{IL}	LOW-level input voltage		0.0	—	0.7	V
VICR	Common-mode input range	CK, CK	0.97	—	1.53	V
V _{ID}	Differential input voltage	CK, CK	360	—	—	mV
I _{ОН}	HIGH-level output current		—	—	-20	mA
I _{OL}	LOW-level output current		—	—	20	mA
T _{amb}	Operating free-air temperature range		0	—	+70	°C

NOTE:

 The RESET input of the device must be held at V_{DD} or GND to ensure proper device operation. The differential inputs must not be floating, unless RESET is low.

DC ELECTRICAL CHARACTERISTICS

Over recommended operating conditions. Voltages are referenced to GND (ground = 0 V).

				LIMITS			
SYMBOL	PARAMETER	TEST CONDITIO	ONS	T _{amb} = 0 to +70 °C			UNIT
			MIN	TYP	MAX	1	
V _{IK}		$I_{I} = -18 \text{ mA}, V_{DD} = 2.3 \text{ V}$		—	—	-1.2	V
Maria		I_{OH} = $-100~\mu\text{A},~V_{DD}$ = 2.3 to 2.7 V		V _{DD} – 0.2	—	—	V
⊻он		$I_{OH} = -16 \text{ mA}, V_{DD} = 2.3 \text{ V}$		1.95	—	—	v
Va		I_{OL} = 100 $\mu A,V_{DD}$ = 2.3 to 2.7 V		—	—	0.2	V
VOL		I_{OL} = 16 mA, V_{DD} = 2.3 V		—	—	0.35	v
lı	All inputs	$V_{I} = V_{DD}$ or GND, $V_{DD} = 2.7$ V		—	—	±5	μΑ
	Static standby	RESET = GND		—	—	0.01	
I _{DD}	Static operating	$\label{eq:RESET} \begin{array}{l} \overline{RESET} = V_{DD}, V_{I} = V_{IH(AC)} \text{ or } \\ \overline{V}_{IL(AC)} \end{array}$	IO = 0, V _{DD} = 2.7 V	_	_	45	mA
	Dynamic operating – clock only	$\label{eq:RESET} \begin{array}{l} \overline{\text{RESET}} = V_{DD}, \ V_{I} = V_{IH(AC)} \ \text{or} \\ V_{IL(AC)}, \ CK \ \text{and} \ \overline{CK} \ \text{switching} \\ 50\% \ \text{duty cycle.} \end{array}$		90	_	_	μ A/ clock MHz
I _{DDD}	Dynamic operating – per each data input	$\label{eq:RESET} \begin{array}{ c c c c } \hline RESET = V_{DD}, V_I = V_{IH(AC)} \text{ or } \\ V_{IL(AC)}, CK \text{ and } \overline{CK} \text{ switching} \\ 50\% \text{ duty cycle. One data input} \\ \text{switching at half clock frequency,} \\ 50\% \text{ duty cycle.} \end{array}$	IO = 0, V _{DD} = 2.7 V	20	_	_	μΑ/ clock MHz/ data input
r _{OH}	Output high	$I_{OH} = -20 \text{ mA}, V_{DD} = 2.3 \text{ to } 2.7 \text{ V}$		7	—	20	Ω
r _{OL}	Output low	I_{OL} = 20 mA, V_{DD} = 2.3 to 2.7 V		7	—	20	Ω
r _{O(Δ)}	r _{OH} − r _{OL} each separate bit	$I_{O} = 20 \text{ mA}, T_{amb} = 25^{\circ}\text{C}, V_{DD} = 2.5 \text{ V}$		—	_	4	Ω
	Data inputs	$V_{I} = V_{REF} \pm 310 \text{ mV}, V_{DD} = 2.5 \text{ V}$		2.5	2.74	3.5	
Ci	CK and CK	$V_{ICR} = 1.25 \text{ V}, V_{I(PP)} = 360 \text{ mV}, V_{I}$	_{DD} = 2.5 V	2.5	3.15	3.5	pF
	RESET	$V_{I} = V_{DD}$ or GND, $V_{DD} = 2.5$ V		_	2.27	—	

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TIMING REQUIREMENTS

Over recommended operating conditions; $T_{amb} = 0$ to +70 °C (unless otherwise noted) (see Figure 1)

			LIM		
SYMBOL	PARAMETER	TEST CONDITIONS	V _{DD} = 2.5	UNIT	
			MIN	МАХ	
f _{clock}	Clock frequency		—	200	MHz
tw	Pulse duration, CK, CK HIGH or LOW		2.5	—	ns
t _{act}	Differential inputs active time	Notes 1, 2	—	22	ns
t _{inact}	Differential inputs inactive time	Notes 1, 3	—	22	ns
	Setup time, fast slew rate (see Notes 4 and 6)		0.		
^L SU	Setup time, slow slew rate (see Notes 5 and 6)		0.9		115
	Hold time, fast slew rate (see Notes 4 and 6)		0.	ns	
τ _h	Hold time, slow slew rate (see Notes 5 and 6)		0		
t _{SL}	Output slew		1	6	V/ns

NOTES:

1. This parameter is not necessarily production tested.

2. Data inputs must be below a minimum time of t_{act} max, after RESET is taken high.

3. Data and clock inputs must be held at valid levels (not floating) a minimum time of tinact max, after RESET is taken low.

4. For data signal input slew rate \geq 1 V/ns.

5. For data signal input slew rate ≥ 0.5 V/ns and < 1 V/ns.

6. CK, \overline{CK} signals input slew rates are ≥ 1 V/ns.

SWITCHING CHARACTERISTICS

Over recommended operating conditions; T_{amb} = 0 to +70 °C; V_{DD} = 2.3 - 2.7 V Class I, V_{REF} = V_{TT} = V_{DD} × 0.5 and C_L = 10 pF (unless otherwise noted) (see Figure 1)

SYMBOL	FROM (INPUT)	то (оитрит)	LIMITS		UNIT
			V _{DD} = 2.5 V ±0.2 V		
			MIN	MAX	
f _{max}			200	—	MHz
t _{pd}	CK and CK	Q	1.1	2.8	ns
t _{PHL}	RESET	Q	1.1	5	ns

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OUTPUT BUFFER CHARACTERISTICS

The following table describes output-buffer Voltage vs. Current (V/I) characteristics that are sufficient to meet the requirements of registered DDR DIMM performance and timings. These characteristics are not necessarily production tested but can be guaranteed by design or characterization. Compliance with these curves is not mandatory if it can be adequately demonstrated that alternate characteristics meet the requirements of the registered DDR DIMM application.

VOLTAGE (V)	PULL-DOWN		PULL-UP		
	I (mA) MIN	I (mA) MAX	I (mA) MIN	I (mA) MAX	
0.0	0	0	0	0	
0.1	7	11	7	10	
0.2	14	23	14	20	
0.3	21	34	21	30	
0.4	28	44	27	40	
0.5	33	54	33	49	
0.6	39	64	38	59	
0.7	44	74	44	68	
0.8	48	83	49	76	
0.9	52	91	53	84	
1.0	56	99	57	93	
1.1	59	107	61	100	
1.2	61	114	64	108	
1.3	63	121	67	115	
1.4	64	127	69	121	
1.5	66	133	70	128	
1.6	66	138	72	134	
1.7	67	142	73	139	
1.8	67	146	74	144	
1.9	67	149	74	148	
2.0	67	151	75	152	
2.1	68	153	75	156	
2.2	68	154	75	159	
2.3	68	155	76	161	
2.4	—	156	—	163	
2.5	_	157	_	165	
2.6	—	157	_	167	
2.7	—	157	_	168	

PARAMETER MEASUREMENT INFORMATION

TEST CIRCUIT



Figure 1. Load circuitry

NOTE:

1. C_L includes probe and jig capacitance.

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Product data

AC WAVEFORMS



Waveform 1. Inputs active and inactive times (see Note 1)



Waveform 2. Pulse duration





NOTES:

- 1. I_{DD} tested with clock and data inputs held at V_{DD} or GND, and I_O = 0 mA.
- 2. All input pulses are supplied by generators having the following characteristics: PRR \leq 10 MHz, Z_O = 50 Ω , input slew rate = 1 V/ns \pm 20% (unless otherwise specified).
- 3. The outputs are measured one at a time with one transition per measurement.
- 4. $V_{TT} = V_{REF} = V_{DD}/2$ 5. $V_{IH} = V_{REF} + 310 \text{ mV}$ (ac voltage levels) for differential inputs. $V_{IH} = V_{DD}$ for LVCMOS input. 6. $V_{IL} = V_{REF} 310 \text{ mV}$ (ac voltage levels) for differential inputs. $V_{IL} = GND$ for LVCMOS input. 7. t_{PLH} and t_{PHL} are the same as t_{pd} .



Waveform 4. Propagation delay times



SSTV16859



SSTV16859

SOT536-1 ►► B A D ball A1 index area Α2 A Е A₁ Å detail X -C ⊷=∨® B e₁ ¢⊘wM // ¥1 C -ДУ e = v (M) A 00000 т R ōōōļōōō Ρ 000000 Ν 000000 е М 000,000 ŧ L 000¦000 Κ 00000 ¥ 000000 J e₂ н 000000 G F Е 000000 Х D 000000 c 000000 в þ 000000 Α 0000000 1 2 3 4 5 6 DIMENSIONS (mm are the original dimensions) Α A₁ A₂ UNIT b D Е е v w У e₁ e₂ У1 0 5 10 mm max. 0.41 1.2 0.51 5.6 13.6 scale mm 1.5 4.0 12.0 0.1 0.2 0.8 0.15 0.1 0.31 0.9 0.41 5.4 13.4 REFERENCES OUTLINE EUROPEAN **ISSUE DATE** VERSION PROJECTION IEC JEDEC EIAJ 99-12-02 \odot SOT536-1 \in + 00-03-04

LFBGA96: plastic low profile fine-pitch ball grid array package; 96 balls; body 13.5 x 5.5 x 1.05 mm

SOT684-1 В D Α terminal 1 index area A₄ A F detail X -C e₁ ДУ 🗕 1/2 e ⊕ ∅ v M C A B // y1 Cе h. ⊕ øw∭ c 28 29 14 ×. 2 2 2 0.0X е œ ŧ 2 œ 80 655 67 Ė_h e₂ 7 Ε pin 1 index 1/2 e Ε â 12 œ 306 <u>___</u> 1 œ 42 000 nnnninnnnnn 56 43 Х -Dh 0 2.5 5 mm scale **DIMENSIONS (mm are the original dimensions)** Α Α4 D⁽¹⁾ E⁽¹⁾ UNIT b Dh Eh е L v w У e₁ e2 У1 max. max. 0.35 8.05 4.45 8.05 4.45 0.50 0.80 0.5 6.5 6.5 0.10 0.10 0.05 0.1 mm 1.00 7.95 4.15 7.95 0.30 0.18 4.15 Note 1. Plastic or metal protrusions of 0.076 mm maximum per side are not included. REFERENCES EUROPEAN OUTLINE ISSUE DATE VERSION PROJECTION IEC JEDEC EIAJ 01-06-12 SOT684-1 MO-220 \odot E.. 01-08-08

HVQFN56: plastic, heatsink very thin quad flat package; no leads; 56 terminals; body 8 x 8 x 0.85 mm

SSTV16859

Product data

Data sheet status

Data sheet status ^[1]	Product status ^[2]	Definitions
Objective data	Development	This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice.
Preliminary data	Qualification	This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.
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[1] Please consult the most recently issued data sheet before initiating or completing a design.

[2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.

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Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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